



Statistical Learning II

Lecture 12 - Kernel methods

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Feature maps

Idea: Introduce a feature map:

$$\boldsymbol{\varphi}: \mathbb{R}^d \to \mathbb{R}^p$$
$$\boldsymbol{x} \mapsto \boldsymbol{\varphi}(\boldsymbol{x})$$

And consider a linear predictor in feature space:

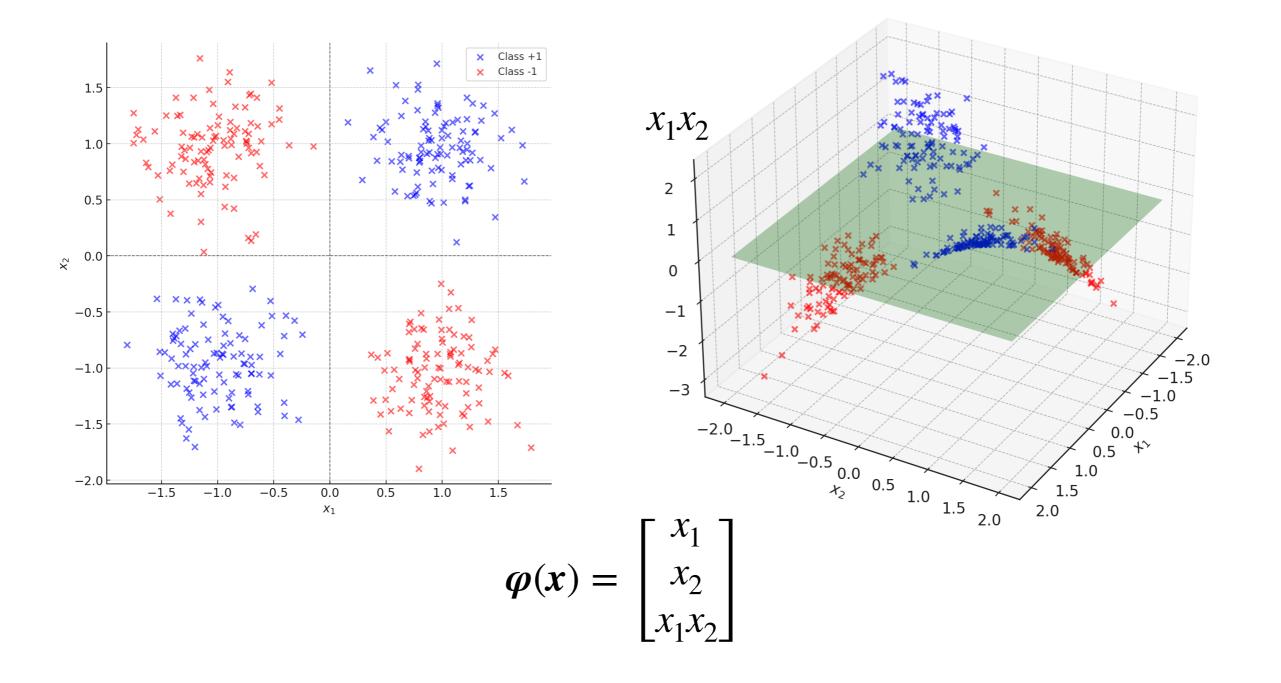
$$f_{\theta}(\boldsymbol{x}) = \langle \boldsymbol{\theta}, \boldsymbol{\varphi}(\boldsymbol{x}) \rangle$$

- Now we have $\theta \in \mathbb{R}^p$.
- f_{θ} still a linear function of θ .
- Typically p > d.
- More generally, we can consider $\boldsymbol{\varphi}: \mathcal{X} \to \mathbb{R}^p$

<u>Example:</u> \mathcal{X} a collection of books.

Examples: XOR Gaussian mixture

$$x \in \mathbb{R}^2$$
 $(d = 2)$ $p(\mathbf{x}) = \frac{1}{4} \sum_{k=1}^4 \mathcal{N}(\boldsymbol{\mu}_k, \boldsymbol{I}_2)$



Let $\mathcal{D} = \{(x_i, y_i) \in \mathcal{X} \times \mathbb{R} : i \in [n]\}$ denote training data and $\varphi : \mathcal{X} \to \mathbb{R}^p$ a feature map.

$$\min_{\boldsymbol{\theta} \in \mathbb{R}^p} \frac{1}{2n} \sum_{i=1}^n (y_i - \langle \boldsymbol{\theta}, \boldsymbol{\varphi}(x_i) \rangle)^2 + \frac{\lambda}{2} ||\boldsymbol{\theta}||_2^2$$

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Defining the feature matrix and label vector:

$$\boldsymbol{\Phi} = \begin{bmatrix} \boldsymbol{\varphi}(x_1) \\ \vdots \\ \boldsymbol{\varphi}(x_n) \end{bmatrix} \in \mathbb{R}^{n \times p} \qquad \boldsymbol{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} \in \mathbb{R}^n$$

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The above admits an explicit solution:

$$\hat{\boldsymbol{\theta}}_{\lambda}(\boldsymbol{\Phi}, \boldsymbol{y}) = (\boldsymbol{\Phi}^{\mathsf{T}}\boldsymbol{\Phi} + n\lambda \boldsymbol{I}_{p})^{-1}\boldsymbol{\Phi}^{\mathsf{T}}\boldsymbol{y}$$

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Note we can equivalently write:

$$\hat{\boldsymbol{\theta}}_{\lambda}(\boldsymbol{\Phi}, \boldsymbol{y}) = \begin{cases} (\boldsymbol{\Phi}^{\mathsf{T}} \boldsymbol{\Phi} + n\lambda \boldsymbol{I}_p)^{-1} \boldsymbol{\Phi}^{\mathsf{T}} \boldsymbol{y} \\ \boldsymbol{\Phi}^{\mathsf{T}} (\boldsymbol{\Phi} \boldsymbol{\Phi}^{\mathsf{T}} + n\lambda \boldsymbol{I}_n)^{-1} \boldsymbol{y} \end{cases}$$



Same result, but one might be cheaper than the other.

Note that the solution:

$$\hat{\boldsymbol{\theta}}_{\lambda}(\boldsymbol{\Phi}, \boldsymbol{y}) = \boldsymbol{\Phi}^{\mathsf{T}} (\boldsymbol{\Phi} \boldsymbol{\Phi}^{\mathsf{T}} + n\lambda \boldsymbol{I}_n)^{-1} \boldsymbol{y}$$

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And the predictor:

$$f_{\theta}(x) = \langle \hat{\boldsymbol{\theta}}_{\lambda}, \boldsymbol{\varphi}(x) \rangle = \langle \hat{\boldsymbol{\alpha}}_{\lambda}, \boldsymbol{\Phi} \boldsymbol{\varphi}(x) \rangle$$



$$f_{\theta}(x) = \langle \hat{\theta}_{\lambda}, \varphi(x) \rangle = \langle \hat{\alpha}_{\lambda}, \Phi \varphi(x) \rangle$$
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Note everything only depends on the scalar product of features

$$K(x, x') = \langle \boldsymbol{\varphi}(x), \boldsymbol{\varphi}(x') \rangle$$

This is also known as a *kernel*.



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This is true for any linear predictor, and goes under the name of "representer theorem"

Kernel methods

As we have shown in the previous examples, it is easier to linearly separate a function in higher dimensions.



<u>Key idea:</u> Take the number of features to infinity $(p \rightarrow \infty)$

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Definition (Hilbert space)

A Hilbert space \mathscr{H} is a vector space (over \mathbb{R} or \mathbb{C}) with an inner product $\langle \cdot, \cdot \rangle_{\mathscr{H}} : \mathscr{H} \times \mathscr{H} \to \mathbb{R}$ which is complete.

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Informally, an inner product is the minimum we need to do linear algebra in infinite dimensions

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$$\langle f, g \rangle_{\mathcal{H}} = \langle g, f \rangle_{\mathcal{H}}$$

- $||f||_{\mathcal{H}}^2 = \langle f, f \rangle_{\mathcal{H}} \ge 0$ with equality iff $f = 0$
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Inner product induces norm, but converse not always true.

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• <u>Complete</u>: Cauchy sequences $f_n \in \mathcal{H}$ converge $f_{\infty} \in \mathcal{H}$

Examples of Hilbert spaces

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• $L^2(\mathbb{R})$: functions $f: \mathbb{R} \to \mathbb{R}$ with $\langle f, g \rangle_{L^2(\mathbb{R})} = \int_{-\infty}^{\infty} f(x)g(x)dx$

Such that:
$$||f||_{L^2(\mathbb{R})}^2 = \langle f, f \rangle_{L^2(\mathbb{R})} = \int_{-\infty}^{\infty} |f(x)|^2 dx < \infty$$

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<u>Idea</u>: Given data $x \in \mathcal{X}$, define features:

$$\varphi: \mathcal{X} \to \mathcal{H}$$
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- <u>Problems</u>: In general $f \notin \mathcal{H}$.
 - Class of functions $f: \mathscr{X} \to \mathbb{R}$ defined this way can be small.

Example

Let $\mathscr{H} \subset \mathbb{R}^2$ with standard Euclidean inner product.

Let $\mathscr{X} = \{x_1, x_2, x_3\}$ be a discrete data space. Define $\varphi : \mathscr{X} \to \mathscr{H}$

$$\varphi(x_1) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \qquad \varphi(x_2) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \qquad \varphi(x_3) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

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For any $\theta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} \in \mathcal{H}$, define the function: $f(x) = \langle \theta, \varphi(x) \rangle$

We have: $f(x_1) = \theta_1$ $f(x_2) = \theta_2$ $f(x_3) = \theta_1 + \theta_2$

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Only few functions on ${\mathcal X}$ can be expressed this way.

e.g. can't express
$$f(x_1) = 1$$
 $f(x_2) = 0$ $f(x_3) = 2$

Reproducing property

To make the Hilbert space compatible with \mathcal{X} , we need the following reproducing property:

Definition (RKHS)

A Hilbert space \mathscr{H} of functions over \mathscr{X} is said to be a "Reproducing Kernel Hilbert Space" (RKHS) if there exists $\varphi \in \mathscr{H}$ such that:

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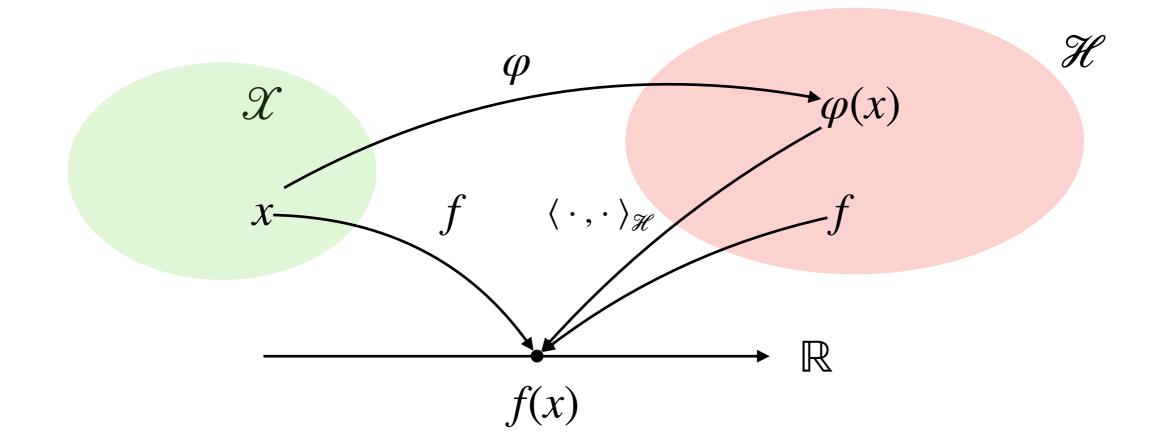
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Let $\mathcal{D} = \{(x_i, y_i) \in \mathcal{X} \times \mathbb{R} : i \in [n]\}$ denote training data. We now have everything we need to define ERM on a RKHS.

$$\min_{f \in \mathcal{H}} \frac{1}{2n} \sum_{i=1}^{n} (y_i - f(x_i))^2 + \frac{\lambda}{2} ||f||_{\mathcal{H}}^2$$

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Closed-form in terms of "infinite dimensional" matrices " $\Phi \in \mathbb{R}^{n \times \infty}$ "?

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As before, defining the kernel function and matrix

$$K(x, x') = \langle \varphi(x), \varphi(x') \rangle_{\mathcal{H}} \qquad K_{ij} = \langle \varphi(x_i), \varphi(x_j) \rangle_{\mathcal{H}}$$

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The solution can be written as:

$$\hat{f}(x) = \sum_{i=1}^{n} \hat{\alpha}_{\lambda,i} K(x, x_i) \qquad \hat{\alpha}_{\lambda}(\boldsymbol{\Phi}, \boldsymbol{y}) = (\boldsymbol{K} + n\lambda \boldsymbol{I}_n)^{-1} \boldsymbol{y}$$

Note that in practice, to do ridge regression on \mathcal{H} we don't even need to know what φ is. It suffices to have K.

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Theorem (Aronszajn, 1950)

A function $K: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ defines a positive definite Kernel if and only if there exists a Hilbert space \mathcal{H} and a map $\varphi: \mathcal{X} \to \mathcal{H}$ such that:

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In words: specifying \mathcal{H} and φ is completely equivalent to specifying K,

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A kernel can correspond to several feature maps. e.g. $\mathcal{X} = \mathbb{R}$

$$\varphi(x) = x$$
 $\varphi(x) = \frac{1}{\sqrt{2}} \begin{bmatrix} x \\ x \end{bmatrix}$ $K(x, x') = xx'$

- Gaussian kernel: $K(x, x') = e^{-\frac{1}{2\sigma^2}||x-x'||_2^2}$ (a.k.a. RBF)
- Laplace kernel:

$$K(\mathbf{x},\mathbf{x}')=e^{-\lambda||\mathbf{x}-\mathbf{x}'||_2}$$

Polynomial kernel:

$$K(\mathbf{x},\mathbf{x}') = (\langle \mathbf{x},\mathbf{x}' \rangle + b)^k$$

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- Polynomial kernel:
- Translational invariant kernels
 - Rotationally invariant kernels

$$K(\mathbf{x},\mathbf{x}') = (\langle \mathbf{x},\mathbf{x}' \rangle + b)^k$$

$$K(x, x') = \kappa(x - x')$$

$$K(\mathbf{x},\mathbf{x}')=\kappa(\langle \mathbf{x},\mathbf{x}'\rangle)$$

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Or any other positive-definite function...

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In general, finding φ associated to these is not obvious.

 $y_i = \sin(x) + \varepsilon$ n = 100 $\varepsilon \sim \mathcal{N}(0, 0.2^2)$ $\lambda = 0.1$

